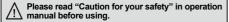
DIN W48×H48mm, W72×H36mm, W72×H72mm counter/timer

Upgraded functions

Upgrade

123458

- Available to set 6 digits(0.00001 to 999999) prescale value (4digit: 0.001 to 9999)
- Built-in Modbus communication function(Communication model)
- Available to set the One-Shot output time in 10ms. (0.01sec. to 99.99sec.)
- Increase contact capacity to 5A(CTS, CTM Series)
- Available to set Count Start Point.(Initial value)
- Improved to select memory protection function in the indicator
- Added BATCH counter function(CTM Series)
- Added Counter Up-1 / Up-2 / Down-1 / Down-2 input modes
- Added Counter TOTAL / HOLD operation modes in the indicator
- Added Timer TOTAL / HOLD / On Time Display operation modes in the indicator
- Added Timer INT2 / NFD / NFD.1 / INTG output modes
- Added Timer range 999.999s / 9999m59 / 99999.9h





DAQMaster(integrated device management program)

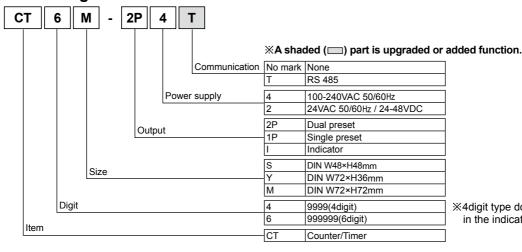
- DAQMaster is a integrated device management program for convenient management of parameters and multiple device data monitoring.
- Visit our website (www.autonics.com) to download user manual and integrated device management program.

Item	Minimum requirements		
System	IBM PC compatible computer with Intel Pentium		
System	III or above		
Operating system	Microsoft Windows 98/NT/XP/Vista/7		
Memory 256MB or more			
Hard disk	More than 1GB of free hard disk space		
VGA	1024×768 or higher resolution display		
Others	RS-232 serial port(9-pin), USB port		

< DAQMaster screen >



Ordering information



X4digit type does not exist in the indicator type.

J-8 **Autonics**

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(I) SSR/ Power controller

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(P) Switching mode power supply

(R) Graphic/ Logic panel

(S) Field network device

Specification	IS
---------------	----

Sories		1110110	CTC		CTV	CTM		
Series		CTS	0	CTY	СТМ			
Digit	<u> </u>		4	6	6	6		
	Dual Preset		CT4S-2P□□	CT6S-2P□□	CT6Y-2P	CT6M-2P		
Model			CT4S-1P□□	CT6S-1P	CT6Y-1P□□	CT6M-1P□□		
Single Preset		-	CT6S-1□□	CT6Y-1□□	CT6M-1			
Digit Size		Preset	11mm	10mm	10mm	13mm		
Size		e Preset	8mm	7mm	7mm	9mm		
Power		Preset		100-240VAC 50/60Hz				
Supply		Preset	24VAC 50/60Hz / 24-4					
Allowable volta			90 to 110% of rated vo	oltage(AC Power type)				
Power	Single	Preset	Max. 12VA					
consumption			AC: Max. 10VA / DC: I					
INA/INB Max			Selectable 1cps / 30cp		kcps			
Min. input	Coun	ter	Reset signal : Selecta	ble 1ms, 20ms				
signal width	Timer		INA, INB RESET : Sel			INA, INH, RESET, INHIBIT, BATCH RESET: Selectable 1ms, 20ms		
Input			Selectable voltage inp [Voltage input] Input in [No-voltage input] Sho	ut or No-voltage input npedance is 5.4kΩ, 'H' ort-circuit impedance :	level : 5-30VDC, 'L' level : 0-2V Max. 1kΩ, Residual voltage : Ma	DC ax. 2VDC		
One-shot out	put		Count, timer : Selectal					
	With-	Contact output	Dual preset : SPST(1a Single preset : SPDT(a) 2EA 1c) 1EA	Dual preset : SPST(1a) 1EA, S Single preset : SPDT(1c) 1EA	PDT(1c) 1EA		
	out com.		Dual preset : 1NPN or Single preset : 1NPN or		1- 0 - 1	Dual preset:3NPN open collector Single preset:2NPN open collector		
Control	With- Contact output		Dual preset : SPST(1a)2EA			Dual preset: SPST(1a), SPDT(1c) Single preset: SPDT(1c)		
output	out com.	Solid state output		,	Dual preset: - Single preset:1NPN open collector	Dual preset:2NPN open collector Single preset:2NPN open collector		
	Wiţh-	Contact output	250VAC 5A resistive lo	oad	250VAC 3A resistive load	250VAC 5A resistive load		
out com. Solid state output			30VDC Max. 100mA Max.					
External sens	or pov	ver	12VDC ±10%, 100mA Max.					
Memory reter	ntion		10years(When using non-volatile semiconductor memory type)					
•	Repe	at error						
T	SET 6	error	Power ON Start : Max. ±0.01% ±0.05 sec Signal Start : Max. ±0.01% ±0.03 sec					
Timer	Voltag	ge error						
	Tempe	erature error						
Insulation res	istanc	е	Min. 100MΩ(500VDC	Megger)				
Dielectric stre	ngth		2,000VAC 50/60Hz for	1minute				
Noise strengt	h (AC	Power)	±2kV the square wave	noise(pulse width:1µs	s) by the noise simulator			
Vibration	Mech	anical	0.75mm amplitude at frequency of 10 to 55(for 1 min.)Hz in each of X, Y, Z directions for 1 hour					
Vibration	Malfu	nction	0.5mm amplitude at fr	0.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 10 minutes				
Shock	Mech	anical	300m/s²(approx. 30G) in each of X, Y, Z directions for 3 times					
SHOCK	Malfu	nction	100m/s²(approx. 10G) in each of X, Y, Z directions for 3 times					
Relay Mechanical		Min. 10,000,000 operations						
		Min. 100,000 operation	ns					
Protection		IP65(Front panel only)						
	Ambio tempo	ent erature	-10 to 55°C, storage :	-25 to 65°C				
Environment	Ambio	ent	35 to 85%RH, storage : 35 to 85%RH					
Approval			CE : FM us					
Unit weight			Approx. 159g		Approx. 149g	Approx. 253q		
			- d - t f		Interior inda	/ IPPION. 2009		

 $[\]ensuremath{\mathbb{X}}\xspace$ Environment resistance is rated at no freezing or condensation.

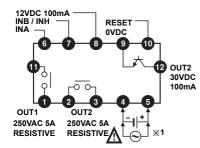
■ Communication specification

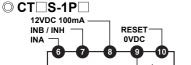
Protocol	Modbus RTU(16bit CRC)
Connection method	RS485
Application standard	Compliance with EIA RS485
Number of connections	31, it is available to set address 1 to 127
Communication method	Half Duplex
Synchronous method	Asynchronous
Communication distance	within max. 800meter
Communication speed	2,400/4,800/9,600/19,200/38,400bps(Factory default : 9,600bps)
Response waiting time	5 to 99ms(Factory default : 20ms)
Start bit	1bit(Fixed)
Data bit	8bits(Fixed)
Parity bit	None, Even, Odd(Factory default : None)
Stop bit	1, 2bit(Factory default : 2bit)

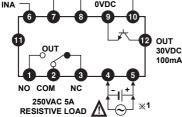
Connections

A Be careful that connections are different between communication model and non-communication model when wiring.

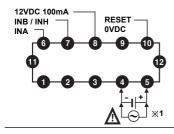




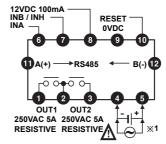




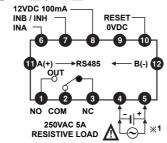
© CT6S-I□



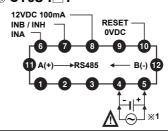
© CT□S-2P□T



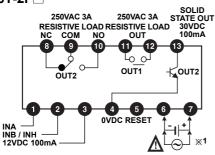
© CT□S-1P□T



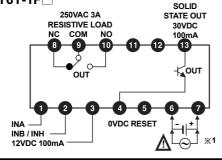
© CT6S-I□T



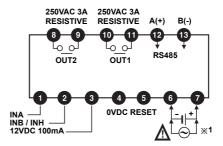
© CT6Y-2P□



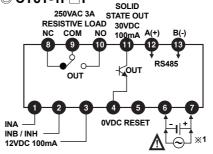
© CT6Y-1P□

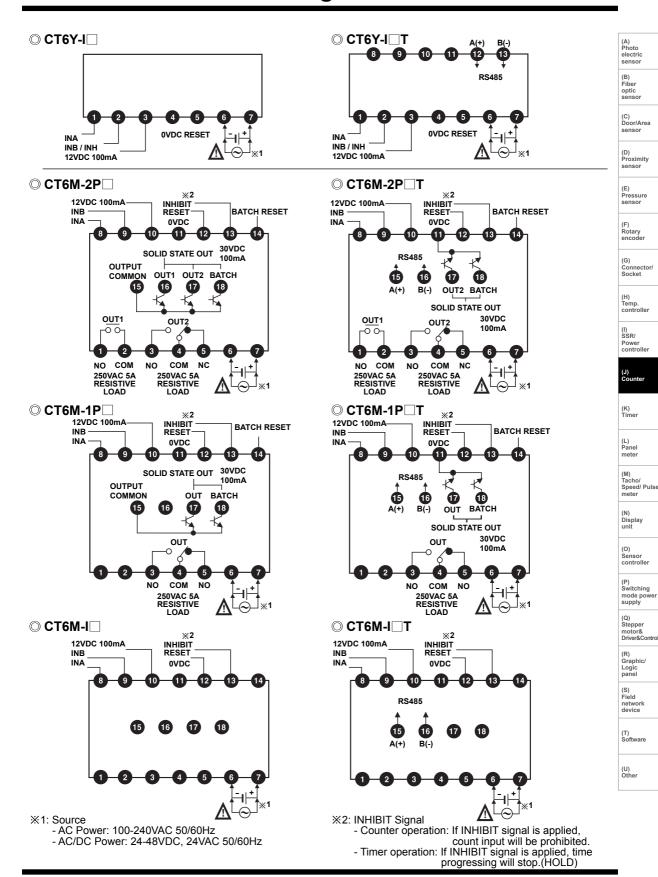


© CT6Y-2P□T



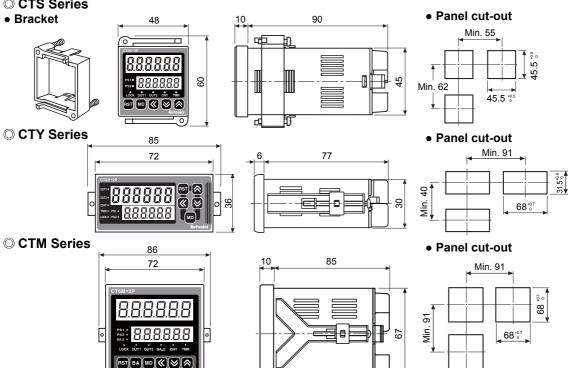
© CT6Y-1P□T







CTS Series



Parts description

CTS Series



CTY Series

Model

CT6M-1P

CT6Y-I

CT6S-I

CT6M-I

CT6Y-1P CT6S-1P PS2→PS

CT4S-1P OUT2→OUT



There are no

PS1, OUT1 LEDs.

There are no PS1, OUT1 OUT2 LEDs.

Changed Notice

CTM Series



(unit:mm)

1. Count indicator(Red LED)

- Run mode
- : Count mode-Indicates count value. Timer mode-Indicates time progressing.
- Function setting mode
- : Indicates function setting mode.

2. Preset value indicator (Yellow-Green LED)

- Run mode: Indicates preset value.

*The indicator type does not exist in CT4S model. - Function setting mode: Indicates setting value1.

- 3. Key Lock: Lights when setting key lock.
- 4. The operation of counter indicator
- 5. The operation of timer indicator
 - TMR LED flashes when the timer is operating. TMR LED lights when the operating time stops

6. Check preset value and display change of it

PS1 LED lights when checking or changing the setting value1. PS2 LED lights when checking or changing the setting value2.

7. Output(OUT1, OUT2) indicator

OUT1 lights when output1 is on.

OUT2 lights when output2 is on.

8. Reset key

By pressing Rsi key in Run mode, the count value is initialized and output is returned.

By pressing RST key in BATCH counter mode, BATCH count value resets



9. Mode key

- By pressing Mokey for 3sec (parameter setting)/ 5sec (communication) in RUN mode, it moves to function setting mode.
- By pressing we key in function setting mode, select function setting mode. By pressing we key over 3 sec., it moves to Run mode.
- By pressing D key over 1 sec. in function setting checking mode, it moves to Run mode.

10. Set key

- : To enter into setting value(PS1, PS2) change status and shift digit of setting value(PS1, PS2).
- : To decrease setting value in setting value change mode, change setting value in function setting mode, move down checked value in function setting check mode.
- To increase setting value in setting value change mode, change setting value in function setting mode, move up checked value in function setting check mode. By pressing MD key over 1 sec. in Run mode, enters into function setting check mode.

11. BATCH key

By pressing BA key in run mode to enter into BATCH counter indication mode.

- 12. BATCH output indicator(red LED)
- 13. BATCH setting value checking and changing indicator (yellow-green LED)

Lights when checking and changing BATCH setting value.

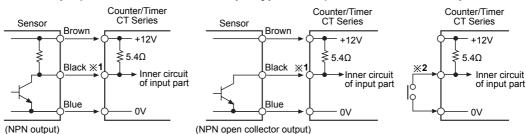
Contact input

Contact input

Input connections

○ No-voltage input(NPN)

• Solid-state input(Standard sensor : NPN output type sensor)

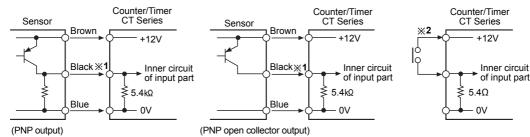


X1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

※2: Counting speed: 1 or 30cps setting(Counter)

Voltage input(PNP)

• Solid-state input(Standard sensor : PNP output type sensor)

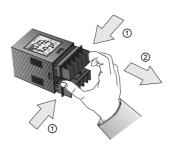


X1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

※2: Counting speed: 1 or 30cps setting(Counter)

■ Input logic Selection[No-voltage input(NPN)/Voltage input(PNP)]

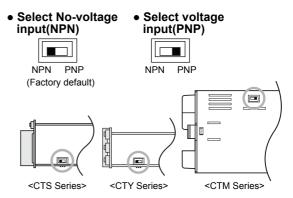
- 1. The power must be cut off.
- 2. Detach the case from the body. (CTS, CTY Series)



* Case detachment Squeeze toward ① and pull toward ② as shown in picture.

Please check if the power is cut off.

Select input logic by using input logic switch(SW1) inside Counter/Timer.



- 4. Push a case in the opposite direction of 2-2.
- 5. Then apply the power to Counter/Timer.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

> F) Rotary encoder

(G)

(H) Temp.

(I) SSR/ Power controller

> (J) Counter

(K) Timer

Panel meter

(M) Tacho/ Speed/ Pulse meter

> (N) Display unit

(O) Sensor controller

(P) Switching mode power supply

(Q) Stepper motor& Driver&Controlle

(R) Graphic/ Logic panel

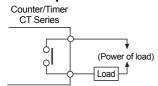
(S) Field network device

> (T) Software

(U) Other

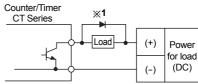
■ Output connections

Contact output



XUse proper load not to exceed the capacity.

O Solid-state output



- **Use proper load and power for load not to excess ON/OFF capacity(30VDC Max. 100mA max.) of solid state output.
- XBe sure not to apply reverse polarity of power.
- X1: When use inductive load(Relay etc), surge absorber (Diode, varistor etc) must be connected between both sides of the load.

■ Factory default

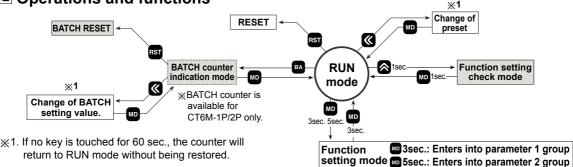
	Parameter	Factory default		
	Input mode (! n)	UP/Down-C (Ud-E)		
	Output mode (allt.ñ)	F (F)		
	CPS (EP5)	30cps (∃□)		
	Indication mode (indicator type)(d5P.ā)	TOTAL (LOERL)		
	OUT2 output time (oUt.2)	Hold (Hold)		
	OUT1 output time (oUE.1)	100ms (00.10)		
ter	Decimal point (dP)			
Counter	Min. reset time (r5 t)	20ms (20)		
0	Input logic (51 5)	NPN (nPn)		
	Prescale decimal point (5 C.dP)	6digit type :, 4digit type :		
	Prescale value (55L)	6digit type: 1.0000 , 4digit type: 1.000		
	Start Point setting (5 t r t)	00000		
	Counting memory (dRER)	Clear (51 r)		
	Lock key (LoCE)	Lock off (L.off)		
	Preset value 1 (PS1)	1000 (1000)		
	Preset value 2 (PS2)	5000 (5000)		
	Time range (Holle /āl a/5EE)	6Digit type: 0.001s-999.999s, 4Digit type: 0.001s-9.999s		
	Up/Down mode (비- 리)	UP (UP)		
	Indication mode(Indicator type)(45P.5)			
	Memory protection(Indicator type) (⊿用上用)	CLEAR (5Lr)		
_	Output mode (๑๕೬ភ)	OND (and)		
Timer	OUT2 output time (oUE2)	Hold (HoLd)		
=	OUT1 output time (oUE 1)	100ms (00.10)		
	Input logic (51 5)	NPN (nPn)		
	Input signal time (F Ā.E)	20ms (20)		
	Lock key (LaCP)	Lock off (L.off)		
	Preset value 1 (PS1)	1000 (1000)		
	Preset value 2 (PS2)	5000 (5000)		
_	Communication address (Pddr)	01 (00)		
Communication	Communication speed (6P5)	9600bps (95)		
l ig	Communication parity (Prty)	NONE (nonE)		
] H	Communication stop bit (5 t P)	2 (?)		
) Ou	Response waiting time (-54)	20ms (20)		
	Communication writing (เอลีย)	Enable (EnA)		

■ Error display

E	Error display		Errors	Output status	How to return
		EEP	Failed in data loading for exsiting setting	OFF	Power on again
	PS1O PS2O	FAIL	values		

J-14 Autonics





O Change of preset(Counter/Timer)

• Even if changing the preset value, input operation and output control will continue. In addition, the preset value could be set to 0 and 0 preset value turns ON. According to output mode, preset value could not be set to 0. (When setting to 0, preset value "0" will flash 3 times.)



In Run mode, it enters into the preset value setting mode using key. 'PS1' LED lights and first digit of preset value flashes.



The preset value is set to ¹/80¹ using ♠, ♠ and ♠ keys, then press ♠ key to enter into the PS2 setting mode.



The preset value is set to '200' using ♠, ♠ and ♠ keys, then press ♠ key to complete PS2 setting and return to Run mode.

Press we key to save set value after changing the setting value. Then, it moves to next parameter or returns to RUN mode. However, if no key is touched for 60 sec., it will return to RUN mode without being saved.

Function setting check mode

Switching display function in preset indicator

• Setting value 1(PS1) and setting value 2(PS2) are displayed each time pressing we key in dual preset model. (In timer, it is available for and, and I, and a output mode.)

© Reset

• In Run mode or function setting mode, if wey or applying the signal to the RESET terminal on the back side, present value will be initialized and output will maintain off status. When selecting voltage input(PNP), short no. 10 and no. 12 terminals, or when selecting no-voltage input(NPN), short no. 11 and no. 12 terminals to reset.

■ BATCH Counter(For CT6M-1P□□ /CT6M-2P□□ model only)

In BATCH counter indication mode, 'BATCH counter value' is displayed in count indicator and 'BATCH counter setting value' is displayed in preset indicator.

Change of BATCH setting value

If pressing A key in Run mode, it will enter into BATCH counter indication mode.



It enters into settingvalue change mode using key. (BA.S lights, first digit of setting value flashes.)



BATCH value is set to '200' using ♠ ♠ and ♠ keys, then press ♠ key to complete BATCH setting value and move to BATCH counter indication mode.

(A) Photo electric sensor

Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor (E) Pressure

(F)

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

> (I) SSR/ Power controller

(J) Counter

> (K) Timer

Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(P) Switching

Switching mode power supply

> Stepper motor& Driver&Controller

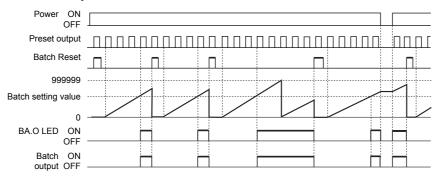
(R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

BATCH counter operation



BATCH counting operation

- BATCH counting value is increasing until BATCH reset signal applied. BATCH counting value will be circulated when it is over 999999.
 - 1) BATCH counting operation in Counter : Counts the number of reaching setting value of CT6M-1P or reaching dual setting value of CT6M-2P□ □
 - 2) BATCH counting operation in Timer: Counts the number of reaching setting time.

(In case of "FLK" output mode, count the number of reaching T.off setting time and T.on setting time.)

BATCH output

- If input signal is applied while changing BATCH setting value, counting operation and output control will be performed.
- If BATCH count value equals to BATCH setting value, BATCH output will be ON and maintain ON status until BATCH reset signal is applied.
- When the power is cut off then resupplied in status of BATCH output is ON, BATCH output maintains ON status until BATCH reset signal is applied.

BATCH reset input

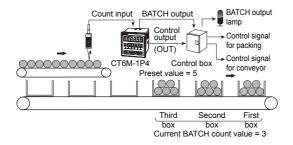
- If pressing reset button or applying the signal to BATCH reset terminal on the back side panel, BATCH counting value will be reset. When selecting voltage input(PNP), short no. 10 and no. 14 terminals, or when selecting no-voltage input(NPN), short no. 11 and no. 14 terminals to reset.
- When BATCH reset is applied, BATCH counting value maintains at 0 and BATCH output maintains in the OFF status.

Application of BATCH counter function

Counter

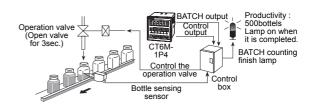
In case, put 5 products in a box then pack the boxes when they reaches to 200.

- Counter preset setting value="5", BATCH setting value="200"
- When the count value of counter reaches to the preset value "5", the control output(OUT) will be on, and at this time the count value of the BATCH counter will be increased by "1". The control box which is received the control output (OUT) repeatedly controls conveyor to move the full box and to place the next empty box for standby. When the BATCH count value reaches to "200", BATCH output will be ON. Then the control box stops conveyor and provides a control signal for packing.

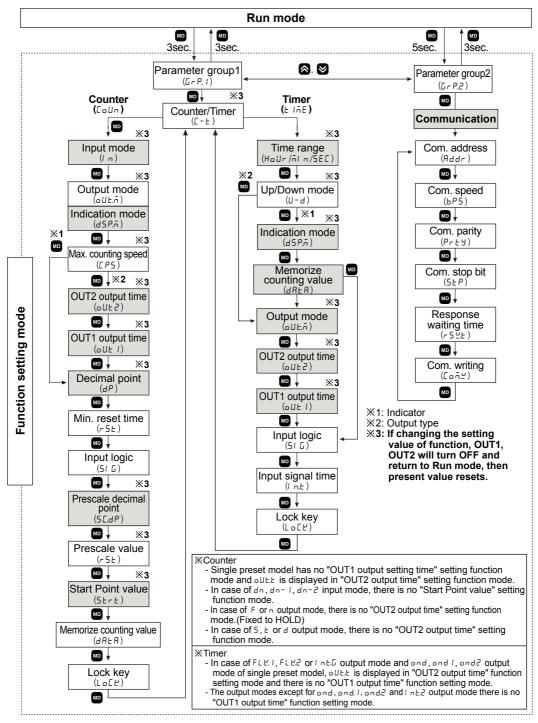


Timer

Fills milk into the bottle for 3sec.(setting time) When 500 bottles are filled, BATCH counting finish lamp is turned on. (Setting time: 3sec., BATCH setting value: 500)



■ Flow chart for function setting mode



XIf changing setting value of parameter group1, display value and output will be initialize.

※Press ■ key over 3sec./5sec. in RUN mode to enter into parameter 1 group/ parameter 2 group.

Press key over 3 sec. in function setting mode to return RUN mode.

XInput operation and output control can be set in function setting mode.

XIf changing set value of X3 marked parameters in function setting mode, OUT1 and OUT2 output will be turned OFF and then the current value is reset.

XParameter 2 group is not available to non-communication models.

sensor (B) Fiber optic sensor (C) Door/Area (D) Proximity (E) Pressure (I) SSR/ (M) Tacho/ Speed/ Pulse (N) Display unit (P) Switching mode powe Logic panel

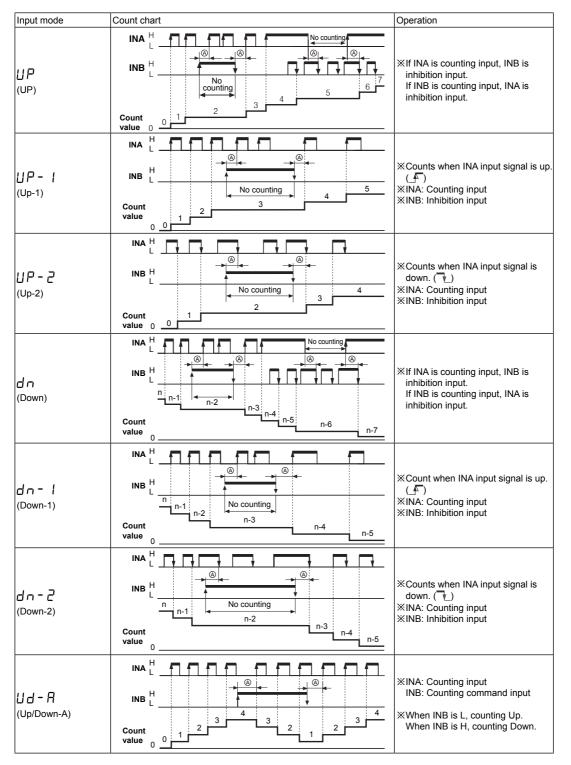
■ Parameter setting(Counter)

(м key: To select setting mode, ✓ or ⋌ key: To change setting value)

Setting mode	How to set
Counter/Timer	₩ConE: COUNTER CoUn ← → Łi nE Łi nE: TIMER
Input mode	Ud-C ←→ UP ←→ UP-1 ←→ UP-2 ←→ dn ←→ dn-1 ←→ dn-2 ←→ Ud-R ←→ Ud-b
Output mode อมะ.กิ Indication mode d5P.กิ	■ UP, UP-1, UP-2 or dn, dn-1, dn-2 input mode F → n → [→ r → r ← r → r → r → r → r → r → r → r
Max. counting speed	**Counting speed is that of one by one(1:1) duty ratio of INA or INB input signal, and it is applied in INA and INB at thesame time. **In case of setting d in output mode, you can choose 1cps, 30cps, 1Kcps.
OUT2 output time	 It is shift flashing digit position of OUT2 output time value. It is shift flashing digit position of OUT2 output time value. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time. It is shift flashing digit position of OUT2 output time.
OUT1 output time	 It is shift flashing digit position of OUT1 output time value. It is shift flashing digit position of OUT1 with flashing digit position of OUT1 output time value. It is displayed by pressing It is displayed by It is displayed by pressing It i
※1 Decimal point dP	6digit type 4digit type **Setting the decimal point is applied same to counting value and setting value.
Min. reset time	/ ← → ≥0 unit: ms
Input logic	nPn: No-Voltage input
** 1 Prescale decimal point 5 C.d P	• 6digit type
Prescale value 5 £ L	
Start Point Value	
Memory protection	
Lock key	LoFF \LoC.1 \XLoFF: Cancellation of the lock mode. \[\begin{align*} \LoC.2: \Locks \& \xi \& \xi \& \xi \\ \LoC.3: \Locks \& \xi \\ \LoC.3: \Locks \& \xi

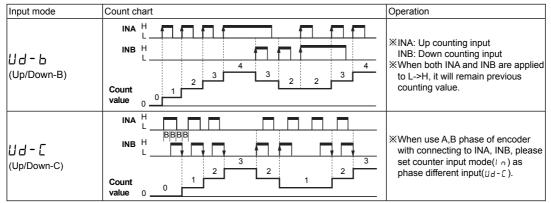
- X1. Explanation of decimal point and prescale decimal point setting
 - Decimal point setting: Set decimal point of the display value on front indicator.
 - Prescale decimal point setting : Set prescale decimal point of counting regardless of decimal point of display value on front indicator.

■ Input operation mode(Counter)



(A) Photo electric sensor (B) Fiber optic senso (C) Door/Area (D) Proximity (E) Pressure sensor (I) SSR/ (M) Tacho/ Speed/ Pulse meter (N) Display unit (P) Switching mode power supply (Q) Stepper motor& Driver&Co (R) Graphic/ Logic panel (S) Field network device

■ Input operation mode(Counter)



※③ signal width should be over min. signal width and ⑤ signal width should be over a half min. signal width.

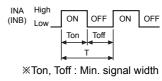
If not, ±1 will occur.

*The meaning of "H" and "L"

	Voltage input (NPN)	No-Voltage input (PNP)		
Н	5-30VDC	Short circuit		
L	0-2VDC	Open		

*Min. signal width by counting speed

Min. signal width
500ms
16.7ms
0.5ms
0.1ms
0.05ms

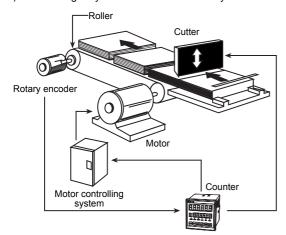


Prescale function(Counter)

This function is to set and indicate calculated unit for actual length, liquid measure, position etc. It is called "Prescale value" for measured length, measured liquid, measured position, etc per 1 pulse.

For example, P is the number of pulses per 1 revolution of a rotary encoder and L is the desired length to be measured. Prescale value is [the desired length (L)]/[the number of pulses (P) per 1 revolution of the rotary encoder.]. It is the length per 1 pulse of a rotary encoder.

Ex) Control length by the counter and the rotary encoder



[In case of 22mm diameter(D) of roller connected with the encoder of 1,000 pulse]

• Prescale value = $\frac{\pi \times \text{Diameter of the roller(D)}}{\text{The number of pulses per}}$ 1 revolution of the encoder

 $= \frac{3.1416 \times 22}{1000}$ = 0.069 mm/pulse

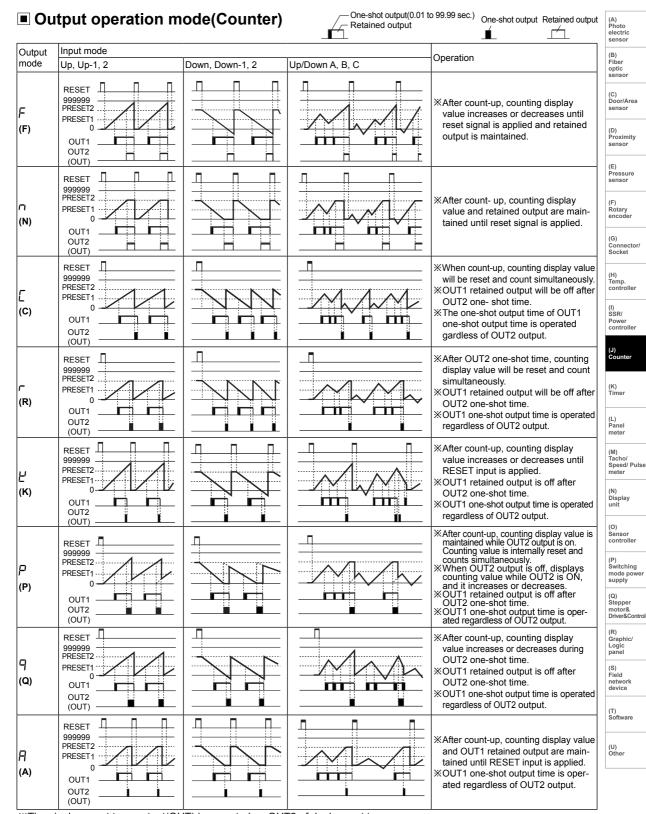
To control conveyor position in 0.1mm, set the decimal point to tenth place(-----) in decimal point setting mode(\mathcal{AP}) and set the prescale decimal point to thousandth place(-----) in prescale decimal point setting mode(\mathcal{ELAP})Then set prescale value "0.069" in prescale setting mode (\mathcal{ELL}).

■ Start point function(Counter)

This function is that start point value works as initial value when on counting mode.

- In case of dn, dn- 1 or dn-2 in timer input mode, it is not available.
- When reset is applied, the present value is initialized to start point.
- After count up in [, r, P, 9 After count up in

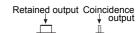
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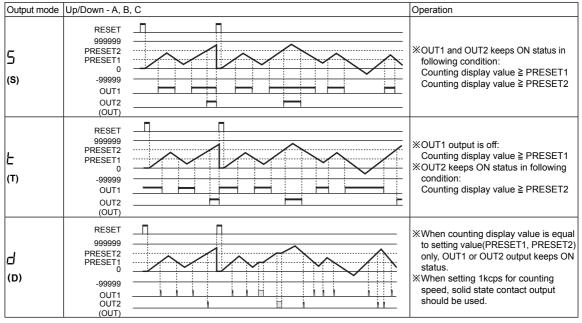


**The single preset type output(OUT) is operated as OUT2 of dual preset type. **OUT1 output could be set to 0 in all modes and 0 value output turns ON.

 $[\]times$ OUT2 output could not set to 0 in C(\mathcal{E}). R(\mathcal{E}), P(\mathcal{E}) or Q(\mathcal{E}) output mode.

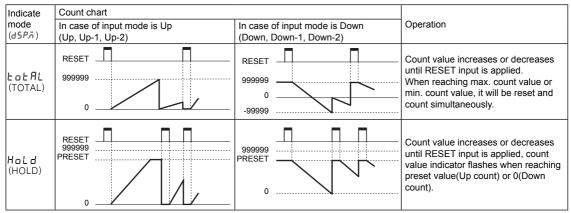
■ Output operation mode(Counter)



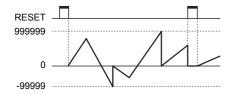


- XThe single preset type output(OUT) is operated as OUT2 of dual preset type.
- XThe dual preset model OUT1 output is operated as one-shot or retained output.(except 5, ₺, ₼ mode)
- XOUT1 output could be set to 0 in all modes and 0 value output turns ON.
- XOUT2 output could not set to 0 in C(E), R(r), P(P) or Q(P) output mode.

Counter operation of the indicator(CT6S-I, CT6Y-I, CT6M-I)



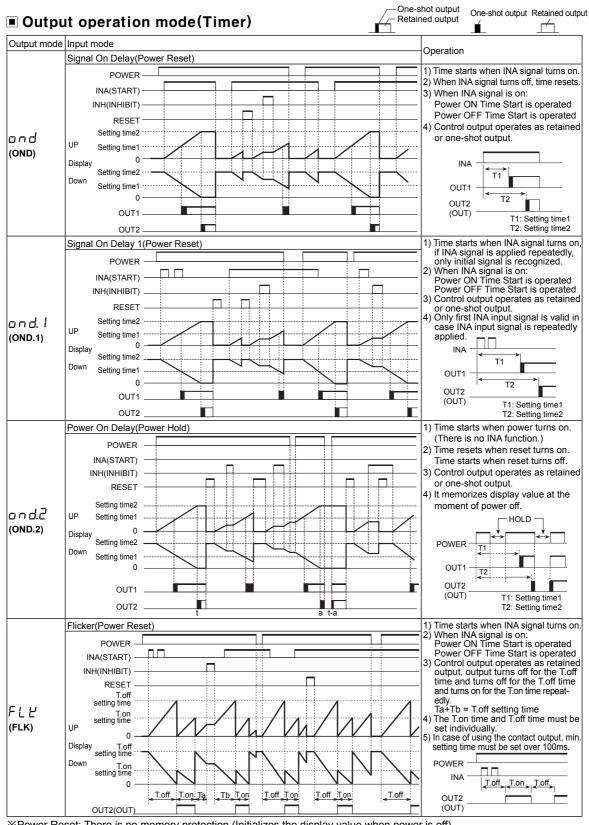
• In case of the input mode is Command input (╝┪-Я), Individual input(╝┪-Ы), Phase difference input(╝┪-С).



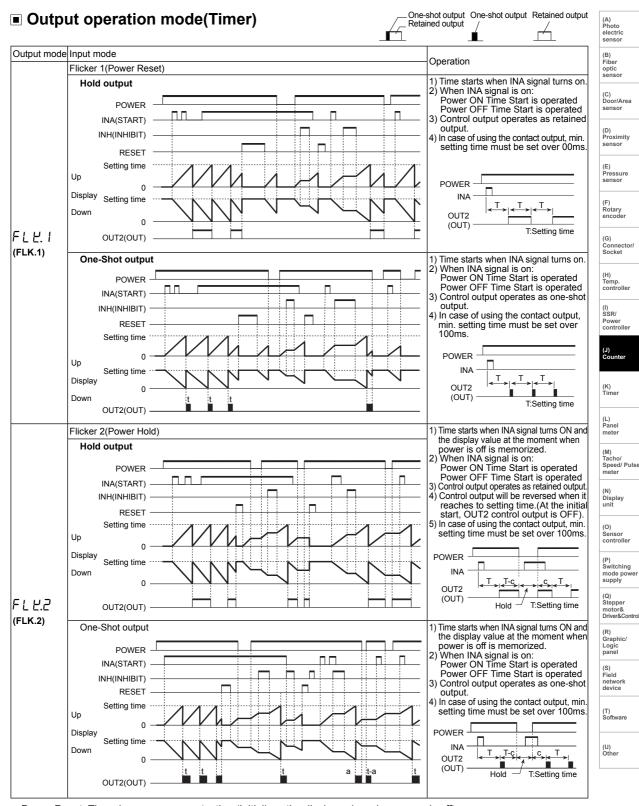
※In case of UP/DOWN (リュー 月、リュー 上、リュー 上) input mode, indication mode (よ5 凡 ふ) of the configuration is not displayed.

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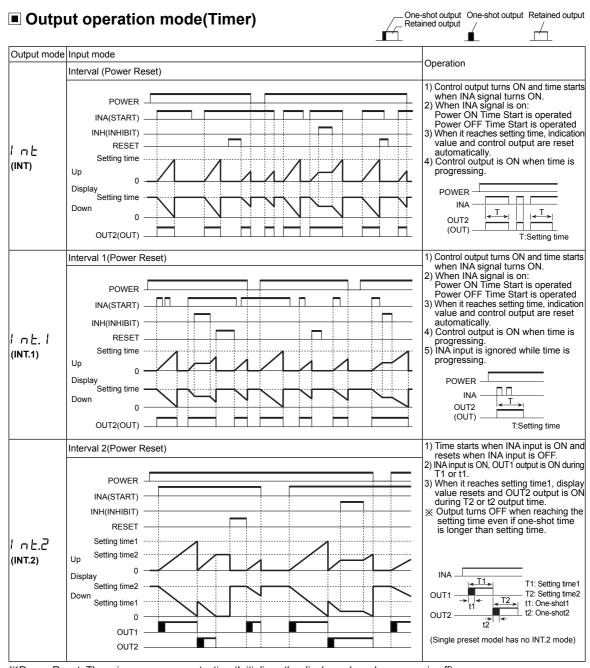
Setting mode	How to set	sensor (B)		
Counter/Timer	XEoUn ← → Łi ōE XEoUn: COUNTER	Fiber optic sensor		
Timer range HoUr /āt n/SEC	● 6digit type SEL	(C) Connector/ Socket (H) Temp. controller (J) Counter		
UP/DOWN mode ಟ - d	9999h 99h59m 9999s 999.9m			
Indication mode	**Used for the indicator only. E □ E R L → H□ L d → □ □ L d	(L) Panel meter		
Memory protection	operation for the indicator'). **Used for the indicator only. **ELr : Initializes time value when power is off.			
dRER .	rEC: Memorizes time value at the moment of power off.	(N) Display unit		
Output mode ๑ ป Ł.กั	ond ←> ond ! ←> ond 2 ←> FLE ←> FLE.! ←> FLE.2 ←> ! nt ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑	(O) Sensor controller		
		(P) Switching mode power supply		
OUT2 output time	## Set OUT2 one-shot output time. ## Setting range: 0.01 to 99.99sec. ## aL d is displayed by pressing ## key 4 times.	(Q) Stepper motor& Driver&Controll		
	⊗ key: To shift flashing digit position of OUT1 output time value. ⊗ & key: To change OUT1 output time value.	(R) Graphic/ Logic panel		
OUT1 output time	XSet OUT1 one-shot output time. XSetting range: 0.01 to 99.99sec., Hold XH□Ld is displayed by pressing key 4 times.	(S) Field network device		
Input logic 5 IE		(T) Software		
Input signal time		(U) Other		
Lock key	LoFF ← LoC. I			



※Power Reset: There is no memory protection.(Initializes the display value when power is off) Power Hold: There is memory protection.(Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

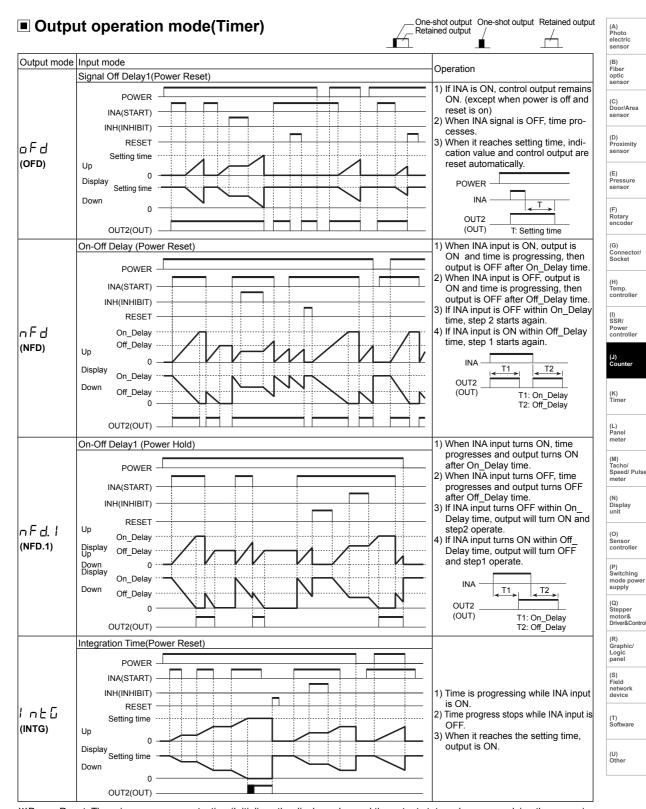


※Power Reset: There is no memory protection.(Initializes the display value when power is off)
Power Hold: There is memory protection.(Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)



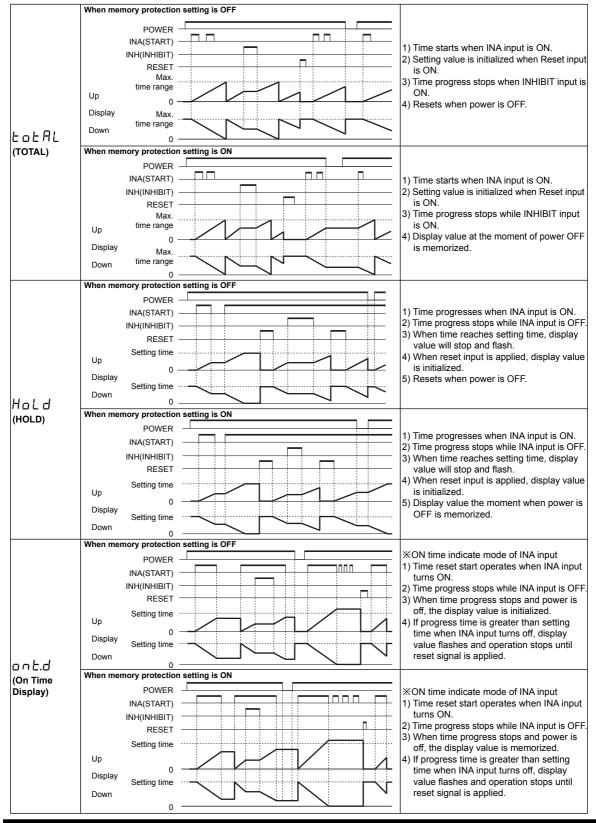
※Power Reset: There is no memory protection.(Initializes the display value when power is off)
Power Hold: There is memory protection.(Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

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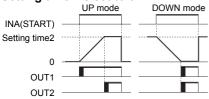
※Power Reset: There is no memory protection.(Initializes the display value and the output status when re-supplying the power.)
Power Hold: There is memory protection.(It memorizes the status of power off. When re-supplying the power, it returns the memorized display value and the output status.)

■ Timer operation of the indicator(CT6S-I, CT6Y-I, CT6M-I)

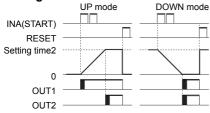


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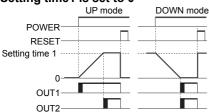
- Timer '0' time setting
- O Available output operation mode to set '0' time setting and, and 1, and 2, and 1, and 2.
- Operation according to output mode(at 0 time setting)
- 1) OND(Signal ON Delay) mode [and]
- Setting time1 is set to 0



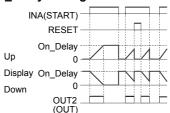
- 2) OND.1(Signal ON Delay 1) mode [and. 1]
- Setting time1 is set to 0



- 3) OND.2(Power ON Delay2) mode [and.2]
- Setting time1 is set to 0

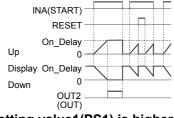


- 4) NFD(ON-OFF Delay) mode [nFd]
- OFF Delay setting time is set to 0

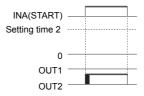


5) NFD.1(ON-OFF Delay1) mode [nFd.1]

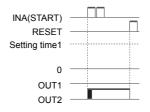
• OFF Delay setting time is set to 0



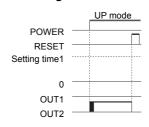
Setting time2 is set to 0



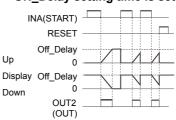
• Setting time2 is set to 0



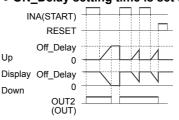
• Setting time2 is set to 0



• ON_Delay setting time is set to 0



• ON_Delay setting time is set to 0



○ Setting value1(PS1) is higher than Setting value2(PS2)

OND(and), OND.1(and.1)or OND.2(and.2)output mode

- UP mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON.
- DOWN mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON.
 If the setting value 1 is same as the setting value2 and START signal is applied, OUT1 output turns ON immediately.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

> F) Rotary encoder

(G) Connector/ Socket

Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

Panel meter (M)

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode power supply

> (Q) Stepper motor& Driver&Controlle

(R) Graphic/ Logic panel

(S) Field network device

> (T) Software

(U) Other

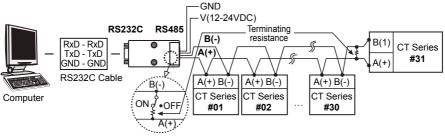
Communication mode

Parameter setting

(MD key: To select setting mode, ✓ or ⋌ key: To change setting value)

Setting mode	How to set					
Com. address	 					
Com. speed (6P5)	24 ←→ 48 ←→ 95 ←→ 192 ←→ 384 ※2400/4800/9600/19200/38400bps					
Com. parity (アトビリ)	nanE ← → EuEn ← → add					
Com. stop bit (5 £ P)	1 ←→ 2					
	XSetting range according to com. speed.					
esponse waiting time	response waiting time. 4800bps 8ms to 99ms					
(r 5 4. E)	☑					
(/	value. 19200bps 5ms to 99ms					
	38400bps 5ms to 99ms					
Com. write	Enfl ← → dl 5fl					

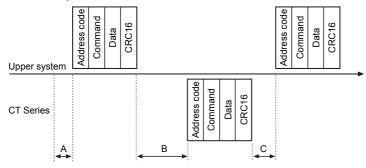
O Application of system organization



XIt is recommended to use communication converter, RS485 to Serial converter(SCM-38I, sold separately), USB to RS485 converter(SCM-US48I, sold separately). Please use a proper twist pair for RS485 communication.

Communication control ordering

- 1. The communication method is Modbus RTU(PI-MBUS-300-REV.J).
- 2. After 1sec. of power supply into the high order system, it starts to communicate.
- 3. Initial communication will be started by the high order system. When a command comes out from the high order system, CT Series will respond.



 $XA \rightarrow Min.$ 1sec. after applying power

- 38400bps: Approx. 1ms. 19200bps: Approx. 2ms.
 - - 9600bps: Approx. 4ms.
 - 4800bps: Approx. 8ms.
 - 2400bps: Approx. 16ms.
- C → Min. 20ms

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O Communication command and block

The format of query and response

1) Read Coil Status(Func 01 H), Read Input Status(Func 02 H

Query(Master)

Slave Address		Starting Address				Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
-							

CRC 16

• Response(Slave)

Slave Address	Function	Byte	Data	Data		Error Ch (CRC 1	
Address		Count				Low Hig	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
			•				

CRC 16

2) Read Holding Registers(Func 03 H), Read Input Registers(Func 04 H)

Query(Master)

Slave Address	Function	Starting Address		INO Of Points		Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

• Response(Slave)

Slave	lave ddress Function Byte Coun Byte 18yte 18yte 18yte		Data		Data		Data		Error Check (CRC 16)	
Address		Count	High	Low	High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

3) Force Single Coil(Func 05 H)

Query(Master)

Slave Address		Coil Address		Force Data		Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
l.							

CRC 16

Response(Slave)

	Slave Address		Coil Address		Force Data		Error Check (CRC 16)	
	Audiess		High	Low	High	Low	Low	High
	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
i							1	

CRC 16

4) Preset Single Register(Func 06 H)

Query(Master)

Slave	i unction	Register Address		Preset [Data	Error Che (CRC 16)									
Address		High	Low	High	Low	Low	High								
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte								
-						ı									

CRC 16

Response(Slave)

Slave	Function	Register Address		Preset Data		Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

5) Preset Multiple Registers(Func 10 H)

Query(Master)

Slave Address	Function	Starti Addre	ng ess	No. o Regis		Byte Count			Data		Error Check (CRC 16)	
		High	Low	High	Low		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
1-											ī	

CRC 16

Response(Slave)

Slave	Eunction	Starting Address		INIO of Pagistar		Error Che (CRC 16)			
Address		High	Low	High	Low	Low	High		
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte		
14									

CRC 16

6) Application

Read Coil Status(Func 01 H)
Master reads OUT2 00002(0001H) to 00003(0002H),
OUT1 output status(ON: 1, OFF: 0) from the
Slave(Address 01).

Query(Master)

Slave Address	Function	Starting Address		NO OF Points		Error Check (CRC 16)				
Address		High	Low	High	Low	Low	High			
01 H	01 H	00 H	01 H	00 H	02 H	EC H	0B H			

On slave side OUT2 00003(0002H) : OFF, OUT1 00002(0001H) : ON

Response(Slave)

Slave Address	Function	Byte Count	Data	Error Check (CRC 16) Low	High
01 H	01 H	01 H	02 H	D0 H	49 H

Read Input Register (Func 04 H)Master reads preset value 21004(03EBH) to 21005(03ECH) of counter/timer, Slave (Address 15).

Query(Master)

Slave	Function			No of Points		Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
0F H	04 H	03 H	EB H	00 H	02 H	00 H	95 H

In case that the present value is 123456(0001 E240 H) in slave side, 31004(03EBH): E240 H, 31005(03ECH): 0001H

Response(Slave)

	Slave Address		Count	Data		Data		Error Check (CRC 16)	
				High	Low	High	Low	Low	High
	0F H	04 H	04 H	E2 H	40 H	00 H	01 H	E2 H	28 H

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor (D) Proximity

(E) Pressure sensor

> (F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

> (J) Counter

Timer

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(P) Switching mode powe supply

(Q) Stepper motor& Driver&Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

Modbus Mapping Table

1) Reset/Output

No(Address)	Func	Explanation	Setting range	Notice
00001(0000)	01/05	Reset	0:OFF 1:ON	
00002(0001)	01	OUT2 output	0:OFF 1:ON	
00003(0002)		OUT1 output		
00004(0003)	01	BATCH output	0:OFF 1:ON	For BATCH output model
00005(0004)	01/05	BATCH resets	0:OFF 1:ON	For BATCH output model

2) Terminal input status

No(Address)	Func	Explanation	Setting range	Notice
10001(0000)	02	INA input status	0:OFF 1:ON	Terminal input status
10002(0001)	02	INB input status	0:OFF 1:ON	Terminal input status
10003(0002)	02	INHIBIT input status	0:OFF 1:ON	Terminal input status
10004(0003)	02	RESET input status	0:OFF 1:ON	Terminal input status
10005(0004)	02	BATCH RESET input status	0:OFF 1:ON	Terminal input status

3) Product Information

No(Address)	Func	Explanation	Notice
30001~30100	04	Reserved	_
30101(0064)	04	Product number H	Model ID
30102(0065)	04	Product number L	IVIOGELID
30103(0066)	04	Hardware version	_
30104(0067)	04	Software version	_
30105(0068)	04	Model no. 1	"CT"
30106(0069)	04	Model no. 2	"6M"
30107(006A)	04	Model no. 3	"-2"
30108(006B)	04	Model no. 4	"PT"
30109(006C)	04	Reserved	—
30110(006D)	04	Reserved	_
30111(006E)	04	Reserved	_
30112(006F)	04	Reserved	_
30113(0070)	04	Reserved	_
30114(0071)	04	Reserved	_
30115(0072)	04	Reserved	_
30116(0073)	04	Reserved	_
30117(0074)	04	Reserved	_
30118(0075)	04	Coil Status Start Address	0000
30119(0076)	04	Coil Status Quantity	_
30120(0077)	04	Input Status Start Address	0000
30121(0078)	04	Input Status Quantity	_
30122(0079)	04	Holding Register Start Address	0000
30123(007A)	04	Holding Register Quantity	_
30124(007B)	04	Input Register Start Address	0064
30125(007C)	04	Input Register Quantity	_

4) Monitoring data

No(Address)	Func	Explanation	Setting range	Notice	
		BA.O LED display status	0:OFF 1:ON	Bit 5	
		OUT2 LED display status	0:OFF 1:ON	Bit 6	
		OUT1 LED display status	0:OFF 1:ON	Bit 7	
		BA.S LED display status	0:OFF 1:ON	Bit 10	
31001 (03E8)	04	LOCK LED display status	0:OFF 1:ON	Bit 11	
		PS2 LED display status	0:OFF 1:ON	Bit 12	
		PS1 LED display status	0:OFF 1:ON	Bit 13	
		TMR LED display status	0:OFF 1:ON	Bit 14	
		CNT LED display status	0:OFF 1:ON	Bit 15	
31002(03E9)	04	Present value of BATCH	0 to 999999	For BATCH output	
31003(03EA)	J-	counter	0 10 000000	model	
31004(03EB)			Counter 6digit type: -99999 to	Use counter and timer in common	
31005(03EC)	04	Present value of counter/timer	4digit type: -999999 4digit type: -999 to 9999 Timer: Within time setting range		
31006(03ED)	04	Display unit	Counter: decimal point of display value Timer: Time range	Counter: 40058 Data Timer: 40102 Data	
31007(03EE)			Counter 6digit type: -99999 to	Llaa aquetae	
31008(03EF)	04	PS(2) setting value	999999 4digit type: -999 to 9999 Timer: Within time setting range	Use counter and timer in common	
31009(03F0)			Counter 6digit type: -99999 to	Use counter	
31010(03F1) 04		PS1 setting value	999999 4digit type: -999 to 9999 Timer: Within time setting range	and timer in common	
31011(03F2)	04	Setting value of BATCH	0 to 999999	Use counter and timer	
31012(03F3)	04	counter	0 10 33333	in common	
31013(03F4)	04	Checking the input logic	0: NPN, 1 : PNP		

• Date format of 31001(03E8) address bit

	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit4	Bit 3	Bit 2	Bit 1	Bit 0
	CNT	TMR	PS1	PS2	LOCK	BA.S	_	_	OUT1	OUT2	BA.O	_	_	_	-	-
ĺ	0 or 1	0	0	0 or 1	0 or 1	0 or 1	0	0	0	0	0					

※2 Words data format: Upper data has high number address. Ex)31004: Present Value(Low Word), 31005: Present Value(High Word)

5) Preset value setting group

No(Address)	Func	Explanation	Setting range	Notice
40001(0000)	03	PS2 setting value	Counter	Use counter and timer
40002(0001)	06 16	PS setting value	6digit type: 0 to 999999	in common
40003(0002)	03	PS1 setting	4digit type: 0 to 9999 Timer: Within time	Use counter and timer
40004(0002)	06 16	value	setting range	in common
40005(0004)	03	BATCH coun-	0 to 000000	Use counter
40006(0005)	06 16	ter setting value	0 to 999999	and timer in common

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(A) Photo electric sensor

(C) Door/Area sensor

(I) SSR/ Power controller

6) Function setting mode (Counter group)

No(Address)	Func	Explanation	Setting range	Notice
40051(0032)	03/06/16	Counter/Timer([- L)	1:CoUn 1:ElñE	Use counter and timer in common
40052(0033)	03/06/16	Input mode(I n)	0: UP 5: dn - 2 1: UP - 1 6: Ud - R 2: UP-2 7: Ud - b 3: dn 8: Ud - [4: dn - 1	_
40053(0034)	03/06/16	Indication mode(d1 5 n̄)	O: E o E A L 1: H o L d	For the indicator
40054(0035)	03/06/16	Output mode(all En)	0: F 3: r 6: 9 9: E 1: n 4: E 7: A 10: d 2: C 5: P 8: 5	_
40055(0036)	03/06/16	Maximum counting speed([P5])	0: I 2: IE 4: IDE 1: 30 3: 5E	_
40056(0037)	03/06/16	OUT2(OUT) output time	0001~9999	unit: ×10ms
40057(0038)	03/06/16	OUT1 Output time	0001~9999	unit: ×10ms
40058(0039)	03/06/16	Decimal point(dP)	0: 2: 4: 1: 3: 5:	4digit type 0: 1: 2: 3:
40059(003A)	03/06/16	Min. reset time(r5 t)	0: 1 1:20	unit: ms
40060(003B)	03/06/16	Prescale decimal point position(5 [L.d)	0: 3: 5: 2: 4:	4digit type 1: 2: 3:
40061(003C) 40062(003D)	03/06/16	Prescale value(5 [L)	6digit type: 0.0000 / to 999999 4digit type: 0.00 / to 9999	Connected with prescale decimal point position
40063(003E) 40064(003F)	03/06/16	Start value(5 t r t)	6digit type: 000000 to 999999 4digit type: 0000 to 9999	Connected with decimal point position of display value
40065(0040)	03/06/16	Memory protection (d R L R)	0: [Lr 1: r E [Use counter and timer
40066(0041)	03/06/16	Lock key(Lo[H)	0: L.oFF 1: LoC. 2: LoC.2 3: LoC.3	in common

7) Function setting mode (Timer group)

No(Address)	Func	Explanation	Setting range	Notice
40101 (0064)	03/06/16	Counter/Timer([- +)	O:CoUn 1:E!ñE	Use counter and timer in common
			4digit type	
40102(0065)	00/00/40	Time range	0: 0.001s to 9.999s 5: 0.1m to 999.9m 1: 0.01s to 99.99s 6: 1m to 9999m 2: 0.1s to 999.9s 7: 1m to 99h59m 3: 1s to 9999s 8: 1h to 9999h 4: 1s to 99m59s	
	03/06/16	(HoUr/āin/5EC)	6digit type 0: 0.001s to 999.999s 1: 0.01s to 9999.99s 2: 0.1s to 9999.9s 3: 1s to 9999999 3: 1s to 9999999 4: 0.01s to 99m59.9s 5: 0.1s to 99m59.9s 11: 0.1h to 99999.9h	_
40103(0066)	03/06/16	UP/Down mode	0: UP 1: dn	_
40104(0067)	03/06/16	Output mode	0: and 3: FLE 7: Int. I 10: nFd 1: and I 4: FLE I 8: Int. I 11: nFd I 2: and I 5: FLE 9: aFd 12: Int. G	_
40105(0068)	03/06/16	OUT2(OUT) Output time	0000 to 9999(0: Hold)	unit: ×10ms
40106(0069)	03/06/16	OUT1 Output time	0000 to 9999(0: Hold)	unit: ×10,ms
40107(006A)	03/06/16	Input signal time(n t)	0: I 1: 20	unit: ms
40108(006B)	03/06/16	Memory protection (d R L R)	0: ELr 1: rEE	Use counter and timer in common
40109(006C)	03/06/16	Lock key(LoEP)	0: L.oFF 1: LoC. 2: LoC.2 3: LoC.3	Use counter and timer in common
40110(006D)	03/06/16	ndication mode (d 5 P.ñ.)	0: totAL 1: Hold 2: ont.d	For the indicator

(M) Tacho/ Speed/ Pulse meter (N) Display unit (P) Switching mode power supply (R) Graphic/ Logic panel J-33

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8) Function setting mode (Communication group)

No(Address)	Func	Explanation	Setting range	Notice
40151(0096)	03/06/16	Com. address (Addr)	1 to 127	-
40152(0097)	03/06/16	Com. speed (b P 5)	0:24 1:48 2:96 3:192 4:384	unit: ×100bps
40153(0098)	03/06/16	Com. parity (Pィヒリ)	0:nonE 1:EuEn 2:odd	
40154(0099)	03/06/16	Stop bit (5 £ P)	0: / 1: 2	
40155(009A)	03/06/16	Response waiting time (r 5 4.6)	05 to 99	unit: ms
40156(009B)	03/06/16	Com. writing ([a ō. =')	0:EnR 1:d/58	_

Exception processing

When communication error occurs, the highest bit of received function is set to 1, then sends response command and transmits exception code.

Slave Address	Function+80H	Exception Code	Error Check(CRC16)		
Slave Address	FUNCTION	Lxception code	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	

- Illeegal Function(Exception Code: 01H): Not supporting command
- Illegal Data Address(Exception Code: 02H): Mismatch between the number of asked data and the number of transmittable data.
- Illegal Data Value(Exception Code: 03H): Mismatch between asked the number of data and transmittable the number of data in device
- Slave Device Failure(Exception Code: 04H): Command is processed incorrectly.

Example)

Master reads output status (ON:1, OFF:0) of non existing coil 01001 (03E8 H) from Slave (Address17).

Query(Master)

Slave Address	Function	Starting Address		No. of Points		Error Check(CRC16)	
Slave Address		High	Low	High	Low	Low	High
11H	01H	03H	E8H	00H	01H	##H	##H

• Response(Slave)

Slave Address	Function + 80H	Exception Code	Error Check(CRC16)	
			Low	High
11H	81H	02H	##H	##H

Read and write of parameter value using communication

Read of the parameter area

00002(OUT2), 00003(OUT1), 00004(BA, 0), 10001 to 10005(Terminal input), 30101 to 30125(Product information), 31001 to 31013(Monitoring data)

Read and write of the parameter area

00001(Reset starts), 00005(BATCH Reset starts), 40001 to 40006(Setting value saving group), 40051 to 40066(Counter setting group), 40101 to 40110(Timer setting group), 40151 to 40156(Communication setting group)

Read of communication

Read parameter value using communication.(Function: 01H, 02H, 03H, 04H)
It is able to read communication regardless of permitting/prohibiting communication writing.

Communication write

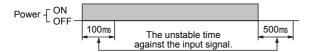
Change parameter value using communication.(Function: 05H, 06H, 10H)

- When change the parameter setting value of 's Function setting mode Counter group' or 's Function setting mode Timer group' using communication, reset indication will flash in 3 sec. and display value will be reset. (Counting display value and progress time before changing parameter setting value are not saved.)
- When change the parameter setting value of Telepreset value setting group' or Telepreset value setting group' or Telepreset value or progress time will not be reset.
- In prohibit writing communication setting ([a-ā,] = 1:dt 5A), a write command does not process.
- If set value beyond the setting range, this setting value is substituted for the value within the setting range and then memorized.

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■ Proper usage

○ The power ON/OFF



Power voltage rises for 100ms after power on and falls for 500ms after power off. Therefore be sure to apply input signal after 100ms and power turns on again after 500ms when power turns off.

 Be sure to use insulated and resistive voltage /current or Class2 supply power device to input 24VAC/24-48VDC power supply model.

Input signal line

- Use as short a cable from the sensor to this unit as possible.
- Use shielded cable for long input line.
- Wire as separating input line from the power line.

When selecting input logic

Be sure that supply power is off when selecting input logic, then select logic input according to input logic changing method.

Contact count input (When it is used as Counter)

If apply contact input at high speed mode(1k, 5k, 10k), it may cause miscount by chattering.

Therefore set low speed mode(1cps or 30cps) at contact input.

- When test dielectric voltage and insulation resistance of the control panel with this unit installed.
- Please isolate this unit from the circuit of control panel.
- Please make all terminals of this unit short-circuited.

O Do not use below places.

- Place where there are severe vibration or impact.
- Place where strong alkalis or acids are used.
- Place where there are direct ray of the sun.
- Place where strong magnetic field or electric noise are generated.

Installation environment

- It shall be used indoor.
- Altitude Max. 2000m
- Pollution Degree 2
- Installation Category II

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

> F) Rotary encoder

Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

imer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode power supply

(Q) Stepper motor&

(R) Graphic/ Logic panel

(S) Field network device

> (T) Software

(U) Other